

# Autonomous Ship Expo

CONFERENCE

JUNE 18, 19 & 20, 2024

RAI AMSTERDAM, NETHERLANDS

# CONFERENCE PROGRAM

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# DAY 1, TUESDAY, JUNE 18

# 09:00 - 12:50 - Perspectives on the deployment of MASS

#### Moderator

James Fanshawe CBE FNI, Chairman, UK MAS Regulatory Working Group, UK

09:00 - Market insights into autonomous maritime systems: an industry survey

Hans-Christoph Burmeister, head of department, Fraunhofer CML, Germany

09:25 - Pro-innovation approaches for testing and assuring MASS

Andre Burgess, assured autonomy program lead, National Physical Laboratory, U

09:50 - MASS and the emergence of maritime intelligent transportation systems

Ørnulf Jan Rødseth, general manager, Norwegian Forum for Autonomous Ships, Norway

10:15 - Highly automated and remote-controlled vessels from an integrator's perspective

Ronny Tomren, vice president remote and digital, Vard Electro, Norway

11:10 - Embracing and navigating the challenges and opportunities in Shipping 4.0

Ivar de Josselin de Jong, director strategy and commercial, Fugro, Netherlands

11:35 - Roadmap toward unmanned surface vehicle (USV) deployment in Malaysia

Farawahida M Monil, principal, geohazards, Petronas, Malaysia

12:00 - MEGURI2040 Stage 2: toward the social implementation of fully autonomous ships

Masanori Muto, group leader/senior researcher, Mitsubishi Research Institute, Japan

12:25 - A flag state perspective of MASS: UK

Simon Ricketts, navigation policy (technology) lead, Maritime and Coast Guard Agency, UK

# 14:00 - 16:35 - Project reviews and case studies

#### Moderator

James Fanshawe CBE FNI, Chairman, UK MAS Regulatory Working Group, UK

14:00 - The operational landscape: a status report from the frontlines

Tom Eystø, CEO, Massterly, Norway

14:25 - Technology development for autonomous and remotely operated ships

Jong Jin Park, principal research engineer, Samsung Heavy Industries, Korea

14:50 - Optimal speed as a basis for fuel-efficient autonomy

Ramon Sieber, research and development engineer, Shiptec, Switzerland

15:45 - Allowing unmanned ships in inland waters

Patrick Potgraven, program manager smart shipping, Ministry of Infrastructure and Water Management, Netherlands

16:10 - Autonomous ships on rivers and in harbors in Taiwan

Chia-Jung (Tina) Hsu, project manager, Ship and Ocean Industries R&D Center (SOIC), Taiwan





























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# DAY 2, WEDNESDAY, JUNE 19

# 09:25 - 12:30 - Legal, liability and regulatory issues

#### Moderator

James Fanshawe CBE FNI, Chairman, UK MAS Regulatory Working Group, UK

09:25 - The MASS assurance and regulatory compliance process

Jan van Tiggelen, discipline leader digital transformation, DNV, Norway

09:50 - Preparation for port state control inspection of MASS

Chris Balls, principal surveyor, Maritime Authority of the Cayman Islands, Cayman Islands

10:15 - Al and its impact on business

Eugene Goryunov, partner, Haynes Boone LLP, USA Vincent Shier, partner, Haynes Boone, USA

10:40 - The evolving approach to maritime autonomy in the United States: Recent U.S. congressional developments, use cases and investment, and the State of U.S. Coast Guard Policy

Sean Pribyl, partner, Holland & Knight LLP, USA

#### 11:30 - Panel Discussion

Jan van Tiggelen, discipline leader digital transformation, DNV, Norway

Chris Balls, principal surveyor, Maritime Authority of the Cayman Islands, Cayman Islands

Eugene Goryunov, partner, Haynes Boone LLP, USA Vincent Shier, partner, Haynes Boone, USA Sean Pribyl, partner, Holland & Knight LLP, USA

# 13:45 - 16:20 - Data connectivity and cybersecurity

#### Moderator

James Fanshawe CBE FNI, Chairman, UK MAS Regulatory Working Group, UK

13:45 - Ship-shore connectivity and remote diagnostics: new BV rule notes

Ilia Maslov, technical advisor - digital and smart ships, Bureau Veritas Marine & Offshore, France

14:10 - Error handling at the core: safe autonomy at TideWise

Sylvain Joyeux, CTO, TideWise, Brazil

14:35 - Advancing autonomous navigation: an Al framework to learn good seamanship

Roberto Galeazzi, head of center, Technical University of Denmark, Denmark

15:30 - COLREG's compliant marine autonomy software – where are we for real today? And how does it work?

Matthew Ratsey, managing director, MarineAI, UK

15:55 - Zero-shot learning for enhanced maritime navigation: a semantic reinforcement approach

**Robert Emmitt**, autonomy and data science engineer II, PacMar Technologies, USA























# DAY 3, THURSDAY, JUNE 20

# 09:25 - 12:25 - Positioning and situation awareness

#### Moderator

James Fanshawe CBE FNI, Chairman, UK MAS Regulatory Working Group, UK

09:50 - Navigation using the Quasi-Zenith Satellite System (QZSS), high-definition maps and positioning

Koki Asari, PhD, general manager, Japan Space Systems, General Incorporated Foundation, Japan

10:15 - Space in support to autonomous shipping

Nil Angli, business applications and partnerships officer, European Space Agency, UK

10:40 - W-band ultra high-resolution radar: The right technology for marine autonomy

Rachael O'Connor, marine business development manager, Navtech Radar, UK 11:35 - Developing a COLREGS-compliant autonomous navigation system

Nigel Lee, chief strategy officer, Robosys Automation, UK

12:00 - Designing for and assuring situational awareness for remote operation

**Matthew Smith,** senior naviation and seamanship engineer, BMT,

Stephen Perry, NATG MASS lead, Naval Authority Technical Group (NATG), UK

# 12:50 - 15:00 - Training and human factors

12:50 - No dropouts, please – creating a future where human ingenuity meets cutting-edge technology

Sinikka Hartonen, secretary general, One Sea Association, Finland

13:15 - Design and optimization of remote operating center

John Cross, faculty, Marine Institute of Memorial University, Canada

13:40 - Navigational training for maritime autonomous surface ships

Zakirul Bhuiyan, director, Warsash MASS Research Centre, UK

14:05 - Introducing Autonomous ships requires a holistic approach.

Antoon van Coillie, director, Zulu Associates/Anglo Belgian Shipping Company, Belgium

14:30 - MASSPeople – integrating AI with MASS technical and engineering competencies: a roadmap for enhanced remote operations

Gordon Meadow, chair IMarEST MASS SIG/founder & CEO, SeaBot XR, UK

\*This program may be subject to change



























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